

Dicussion before the lecture

Reparametrization example by “shifting the phase”

$$\dot{\tilde{\gamma}}(t) = \dot{\gamma}(\phi(t))\phi'(t)$$

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$$\gamma(t) := (\cos(t), \sin(t))$$

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$$\tilde{\gamma}(t) := (\cos(t + \pi/2), \sin(t + \pi/2))$$

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$$\tilde{\gamma}(t) := \gamma(\phi(t))$$

Regular parametrization

Definition.

The point $\gamma(t)$

Regular parametrization

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The point $\gamma(t)$ of γ :

Regular parametrization

Definition.

The point $\gamma(t)$ of $\gamma : (\alpha, \beta) \rightarrow$

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The point $\gamma(t)$ of $\gamma : (\alpha, \beta) \rightarrow \mathbb{R}^2$

Regular parametrization

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Example. $\gamma(t) = (t^3, t^3)$ is singular at 0 because $\dot{\gamma}(t) = (3t^2, 3t^2)$.

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$$\psi(\phi(t)) = t$$

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$\psi(\phi(t)) = t$ for each t

$\psi'(\phi(t))\phi'(t) = 1$ for each t

So, $\psi'(\phi(t)) \neq 0$ and $\phi'(t) \neq 0$ for each t

So, $\psi'(t) \neq 0$ and $\phi'(t) \neq 0$ for each t because ϕ is bijective. \square

Regular parametrization

Proposition. *A reparametrization of a regular parametrization*

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Proposition. A reparametrization of a regular parametrization is regular. □

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The point $\gamma(t)$ of $\gamma : (\alpha, \beta) \rightarrow \mathbb{R}^2$ is regular point if *Proof.*

$\dot{\gamma}(t) \neq 0$ and singular if $\dot{\gamma}(t) = 0$. The parametrization $\gamma :$

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$\dot{\gamma}(t) \neq 0$ and singular if $\dot{\gamma}(t) = 0$. The parametrization $\gamma : (\alpha, \beta) \rightarrow \mathbb{R}^2$ γ is called regular if $\dot{\gamma}(t) \neq 0$ for every $t \in (\alpha, \beta)$. $\tilde{\gamma} : (\tilde{\alpha}, \tilde{\beta}) \rightarrow \mathbb{R}^2$ \square

Example. $\gamma(t) = (t^3, t^3)$ is singular at 0 because $\dot{\gamma}(t) = (3t^2, 3t^2)$.

Lemma.

If $\phi : (\tilde{\alpha}, \tilde{\beta}) \rightarrow (\alpha, \beta)$ is invertible with inverse $\psi : (\alpha, \beta) \rightarrow (\tilde{\alpha}, \tilde{\beta})$, then $\phi'(t) \neq 0$ for all $t \in (\tilde{\alpha}, \tilde{\beta})$ and $\psi'(t) \neq 0$ for all $t \in (\alpha, \beta)$.

Proof.

$\psi(\phi(t)) = t$ for each t

$\psi'(\phi(t))\phi'(t) = 1$ for each t

So, $\psi'(\phi(t)) \neq 0$ and $\phi'(t) \neq 0$ for each t

So, $\psi'(t) \neq 0$ and $\phi'(t) \neq 0$ for each t because ϕ is bijective. \square

Regular parametrization

Proposition. A reparametrization of a regular parametrization is regular.

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$\tilde{\gamma}(\tilde{t})$

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$$\begin{aligned}\tilde{\gamma} : (\tilde{\alpha}, \tilde{\beta}) &\rightarrow \mathbb{R}^2 \\ \tilde{\gamma}(\tilde{t}) &= \gamma(\phi(\tilde{t}))\end{aligned}$$

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$$\tilde{\gamma}(\tilde{t}) = \gamma(\phi(\tilde{t}))$$

$$\tilde{\gamma}'(\tilde{t}) = \gamma'(\phi(\tilde{t}))\phi'(\tilde{t})$$

$$\text{But, } \gamma'(t) \neq 0$$

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If $\phi : (\tilde{\alpha}, \tilde{\beta}) \rightarrow (\alpha, \beta)$ is invertible with inverse $\psi : (\alpha, \beta) \rightarrow (\tilde{\alpha}, \tilde{\beta})$, then $\phi'(t) \neq 0$ for all $t \in (\tilde{\alpha}, \tilde{\beta})$ and $\psi'(t) \neq 0$ for all $t \in (\alpha, \beta)$.

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But, $\gamma'(t) \neq 0$ for all t , therefore, even for $\phi(\tilde{t})$

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If $\phi : (\tilde{\alpha}, \tilde{\beta}) \rightarrow (\alpha, \beta)$ is invertible with inverse $\psi : (\alpha, \beta) \rightarrow (\tilde{\alpha}, \tilde{\beta})$, then $\phi'(t) \neq 0$ for all $t \in (\tilde{\alpha}, \tilde{\beta})$ and $\psi'(t) \neq 0$ for all $t \in (\alpha, \beta)$.

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$\tilde{\gamma} : (\tilde{\alpha}, \tilde{\beta}) \rightarrow \mathbb{R}^2$
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Inner product:

Inner product:

$$v = (2, 3)$$

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$$v = (2, 3)$$

$$w = (2, 1)$$

Inner product:

$$v = (2, 3)$$

$$w = (2, 1)$$

$$v \cdot w$$

Inner product:

$$v = (2, 3)$$

$$w = (2, 1)$$

$$v \cdot w := (2, 3) \cdot (2, 1)$$

Inner product:

$$v = (2, 3)$$

$$w = (2, 1)$$

$$v \cdot w := (2, 3) \cdot (2, 1) = 2 \times 2 + 3 \times 1$$

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$$v = (2, 3)$$

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$$v \cdot w := (2, 3) \cdot (2, 1) = 2 \times 2 + 3 \times 1 = 7$$

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In general:

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In general:

$$(x_1, y_1) \cdot (x_2, y_2) := x_1 x_2 + y_1 y_2$$

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Exercise. For $\mathbf{v} : (\alpha, \beta) \rightarrow \mathbf{R}^2$

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$$\|(x, y)\| = \sqrt{x^2 + y^2}$$

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$$v = (x, y)$$

$$v \cdot w = \|v\| \|w\| \cos(\theta) \text{ where,}$$

θ is the angle between v and w

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Definition. $\gamma : (\alpha, \beta) \rightarrow \mathbf{R}^2$ is a unit speed parametrization

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