Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

It will be important to be absolutely clear about this

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

So we can write any vector as linear combination of them

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

And the coefficients can be recovered by a dot product

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

$$v.\mathbf{e}_{1} = 0$$

$$v.\mathbf{e}_{2} = 0$$

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

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Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

A vector perpendicular to two of the basis vectors will have to be in the direction of the third

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$

We continue our study of the consequences of a curve being on a surfaces

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
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Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

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Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$
 unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

As usual, we study the surface with a surface patch

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

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$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

$$\sigma: U \to S$$
 a regular surface patch.  
 $\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$ 

$$\mathbf{\hat{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

A regular surface has a natural normal.

#### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\mathbf{\hat{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

Try to solve this exercise (Hint:  $\mathbf{T}(t)$  is in the span of?)

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\mathbf{\hat{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

The following discussion is motivated by this intuitive obervation:

### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

The curve lies on a surface because

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\ddot{\gamma}(t).\mathbf{\hat{n}}(\gamma(t))$$

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
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$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

This is obviously normal to the surface

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

The magnitude of this components is called the normal curvature

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

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So, 
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 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

If we subtract this component, what direction does the rest point in?

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

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$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

As we have seen before, we can find that if we find two orthonormal vectors

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

that both are perpendicular to

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

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$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

and then take the cross product

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

The acceleration is already perpendicular to the unit tangent

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

So is the component in the direction of the normal

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\alpha_{2} = \alpha_{2} = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

Therefore, so is the difference

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

because they both lie in the plane perpendicular to  ${f T}$ 

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

Also, since we have removed the component of the normal, it must be perpendicular to it

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

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If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) =??$ 

So we know that it will be perpendicular to  $\hat{\mathbf{n}}$  and  $\mathbf{T}$ 

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_q(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$ 

Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_{2} - \alpha_{2} - 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$  unit speed

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

And is therefore some scalar multiple of  $\hat{\mathbf{n}} \times \mathbf{T}$ 

#### Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$   $\kappa_g(t) \text{ is the geodesic curvature}$ 

# Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

 $\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$   $\kappa_g(t) \text{ is the geodesic curvature}$ 

$$\kappa_q(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

Taking the dot product with  $\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)$  on both sides of the above equation

#### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

# $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ unit speed $\ddot{\gamma}(t).\mathbf{T}(t) = 0$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

Rearranging

#### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$  unit speed  $\ddot{\alpha}(t) \mathbf{T}(t) = 0$ 

$$\ddot{\gamma}(t).\mathbf{T}(t) = 0$$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

 $\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$  (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_q(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

Plugging in the formula for normal curvature as defined above

#### Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

# $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ unit speed $\ddot{\gamma}(t).\mathbf{T}(t) = 0$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$
$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$

Taking dot product with itself (on both sides)

## Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

# $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ unit speed $\ddot{\gamma}(t).\mathbf{T}(t) = 0$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

But the left hand side is the square of the usual curvature!

## Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

Remember that when we viewed the curve simply as a space curve,

## Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

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So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

 $\mathbf{T}(t)$ ,  $\mathbf{N}(t)$ , and  $B(t) := \mathbf{T}(t) \times \mathbf{N}(t)$  proved to be a useful basis

## Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

Now, viewing the curve as a curve on the surface

## Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\kappa_g(t) \text{ is the geodesic curvature}$$

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

 $\mathbf{T}(t)$ ,  $\hat{\mathbf{n}}(t)$ , and  $\mathbf{T}(t) \times \hat{\mathbf{n}}(t)$  proves to be a useful basis

## Recall:

Consider an orthonormal basis  $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

$$\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$$
 unit speed  $\ddot{\gamma}(t).\mathbf{T}(t) = 0$ 

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

**Exercise.** Prove that  $\mathbf{N}(t) = \hat{\mathbf{n}}(t)$  if and only if  $\kappa_g(t) = 0$ 

However,  $\mathbf{N}$  and  $\hat{\mathbf{n}}$  need not coincide, as this simple exercise shows!

## Recall:

Consider an orthonormal basis  $\{e_1, e_2, e_3\}$ .

$$v = \alpha_1 \mathbf{e}_1 + \alpha_2 \mathbf{e}_2 + \alpha_3 \mathbf{e}_3$$

$$\alpha_i = v.\mathbf{e}_i$$

If v is perpendicular to  $\mathbf{e}_1$  and  $\mathbf{e}_2$ 

$$\alpha_1 = v.\mathbf{e}_1 = 0$$

$$\alpha_2 = v.\mathbf{e}_2 = 0$$

So, 
$$v = \alpha_3 \mathbf{e}_3$$

# $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ unit speed $\ddot{\gamma}(t).\mathbf{T}(t) = 0$

 $\sigma: U \to S$  a regular surface patch.

$$\hat{\mathbf{n}}(p) := \frac{\sigma_x(p) \times \sigma_y(p)}{\|\sigma_x(p) \times \sigma_y(p)\|}$$

**Exercise.** Prove that  $\hat{\mathbf{n}}(\gamma(t))$  is perpendicular to  $\mathbf{T}(t)$ .

$$\kappa_n(t) := \ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t))$$
 (normal curvature)

$$\ddot{\gamma}(t) - (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t)) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

 $\kappa_g(t)$  is the geodesic curvature

$$\kappa_g(t) = \ddot{\gamma}(t).(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t))$$

$$\ddot{\gamma}(t) = \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + (\ddot{\gamma}(t).\hat{\mathbf{n}}(\gamma(t)))\hat{\mathbf{n}}(\gamma(t))$$

$$= \kappa_g(t)(\hat{\mathbf{n}}(\gamma(t)) \times \mathbf{T}(t)) + \kappa_n(t)\hat{\mathbf{n}}(\gamma(t))$$

$$\|\ddot{\gamma}(t)\|^2 = \kappa_g^2(t) + \kappa_n^2(t)$$
$$\kappa^2(t) = \kappa_g^2(t) + \kappa_n^2(t)$$

**Exercise.** Prove that  $\mathbf{N}(t) = \hat{\mathbf{n}}(t)$  if and only if  $\kappa_g(t) = 0$ 

**Definition.** A parametrization  $\gamma$  of a curve on a surface is called a geodesic if  $\kappa_g(t) = 0$  for all t.

Such curves are called geodesics

$$\gamma:(\alpha,\beta)\to S$$

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

As we have seen, chain rule expresses the velocity vector in terms of  $\sigma_x$  and  $\sigma_y$ 

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

So we can do the same for the dot with itself, to know its norm

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

Let us abstract out the terms that refer to only the patch

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

Note that E, F, and G are functions with domain U (i.e. domain of  $\sigma$ )

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

They may be computed for a surface patch

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

and used for any curve we may want to study on that patch

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

just like we computed  $\sigma_x$ ,  $\sigma_y$  and used it for the velocity of any curve

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t))$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

So the norm can be also be written in terms of E, F, and G,

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\begin{split} \dot{\gamma}(t).\dot{\gamma}(t) &= x'^2(t)E(x(t),y(t)) \\ &+ 2x'(t)y'(t)F(x(t),y(t)) \\ &+ y'^2(t)G(x(t),y(t)) \\ \|\dot{\gamma}(t).\dot{\gamma}(t)\| &= \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} \end{split}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$$

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) ||\dot{\gamma}(t).\dot{\gamma}(t)|| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^t ||\dot{\gamma}(t)|| \mathrm{d}t$$

and, therefore, the arc length

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^{t} ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^{t} \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

can also be expressed in terms of E, F, and G

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^{t} ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^{t} \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

To summarize, we compute E, F, and G for each point of the surface patch and keep it aside

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^t ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^t \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

Given a curve, we take express it in terms of the surface patch

 $\gamma: (\alpha, \beta) \to S \subset \mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^t ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^t \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

, i.e. find out its (x(t), y(t))

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^t ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^t \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

use that to find out its x'(t) and y'(t) and plug it into the above formula.

 $\gamma:(\alpha,\beta)\to S\subset\mathbb{R}^3$ 

 $\sigma: U \to S$  a regular surface patch.

$$\gamma(t) = \sigma(x(t), y(t))$$

$$\dot{\gamma}(t) = x'(t)\sigma_x(x(t), y(t)) + y'(t)\sigma_y(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)(\sigma_{x}(x(t), y(t)).\sigma_{x}(x(t), y(t)) + 2x(t)'y'(t)(\sigma_{x}(x(t), y(t)).\sigma_{y}(x(t), y(t)) + y'^{2}(t)(\sigma_{y}(x(t), y(t)).\sigma_{y}(x(t), y(t))$$

$$\dot{\gamma}(t).\dot{\gamma}(t) = x'^{2}(t)E(x(t), y(t)) + 2x'(t)y'(t)F(x(t), y(t)) + y'^{2}(t)G(x(t), y(t)) \|\dot{\gamma}(t).\dot{\gamma}(t)\| = \sqrt{x'^{2}(t)E + 2x'(t)y'(t)F + y'^{2}(t)G}$$

where,

$$E(x,y) := \sigma_x(x,y).\sigma_x(x,y)$$

$$F(x,y) := \sigma_x(x,y).\sigma_y(x,y)$$

$$G(x,y) := \sigma_y(x,y).\sigma_y(x,y)$$

$$s(t) = \int_{t_0}^t ||\dot{\gamma}(t)|| dt$$
$$= \int_{t_0}^t \sqrt{x'^2(t)E + 2x'(t)y'(t)F + y'^2(t)G} dt$$

Observe,

$$\dot{\gamma}(t).\dot{\gamma}(t) = \begin{pmatrix} x'(t) & y'(t) \end{pmatrix} \begin{pmatrix} E & F \\ F & G \end{pmatrix} \begin{pmatrix} x'(t) \\ y'(t) \end{pmatrix}$$

Later, it will prove useful to know that E, F, and G can be arranged in a matrix